Filtering With Confidence: In-sample Confidence Bands For GARCH Filters

Marcin Zamojski

University of Gothenburg

ES NASM, St. Louis June 17, 2017

Paper/slides @ zamojski.net



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Correlation

Lucas, Schwaab, and Zhang (2015 JAE), Oh and Patton (2017 JBES)



Systemic risk

Lucas, Schwaab, and Zhang (2015 JAE), Oh and Patton (2017 JBES)



Loss-Given-Default Creal, Schwaab, Koopman, and Lucas (2014 REStat)



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Term structure of interest rates

slope from Diebold, Li, Yue (2008 JE)



Stochastic Volatility with jumps

Johannes, Polson, Stroud (2009 RFS)



Business and financial cycles

Galati, Hindrayanto, Koopman, and Vlekke (2015 EL)





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Loss-Given-DeQ: Is it possible to plot confidence bands around such paths?



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Loss-Given-DeQ: Is it possible to plot confidence bands around such paths?

A: No. Now, yes.



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Motivation, main results

GARCH(1,1) volatility of S&P 500 returns. 2008–2012.



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• A novel bootstrap + a new resampling scheme.

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- A novel bootstrap + a new resampling scheme.
- Bootstrapping conditionally on observed data (vs. the typical unconditional procedures).
- Resampler constructs series which mimic dependence patterns in the data.



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- Produces in-sample confidence bands around time-varying parameters in observation-driven models.
- Accounts for parameter and filtering uncertainty.
- Empirically good coverage properties.
- Both an easily implementable and a flexible method.



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Outline

- ODMs vs. PDMs
- Volatility modelling
- Bootstrap
- Resampler

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- Simulations





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- No time ③
- Conclusions

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Observation-driven

Observation equation:

$$y_t \sim p\left(y_t | Y_{t-1}, \boldsymbol{f}_t; \boldsymbol{\theta}\right),$$
$$Y_t = \{y_1, \dots, y_t\}.$$

Parameter-driven

Observation equation:

 $\begin{aligned} y_t &\sim p\left(y_t | Y_{t-1}, \boldsymbol{f}_t; \boldsymbol{\theta}\right), \\ Y_t &= \left\{y_1, \dots, y_t\right\}. \end{aligned}$

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$$\mathbf{f}_{t+1} = \phi\left(\mathbf{\zeta}_t, \mathbf{f}_t\right),$$

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 $\mathbf{f}_{t+1} = \boldsymbol{\omega} + \mathbf{B}\mathbf{f}_t + \mathbf{A}\mathbf{s}_t(\mathbf{y}_t, \mathbf{f}_t).$

The usual treatment imposes a linear, autoregressive updating function with an innovation equal to the score of the criterion function with respect to the time-varying parameter, f_{f} .

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The gist: a Gauss-Newton update in the time dimension based on the locally observed misfit.

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Members of this class: *anything-*GARCH, ACD, DCC, dynamic copulas

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Volatility modelling

Observation-driven

GARCH(1,1)

$$\begin{split} \mathbf{y}_t &= \varepsilon_t, \\ \varepsilon_t &= \eta_t \sqrt{\sigma_t^2}, \qquad \eta_t \sim \mathsf{N}\left(0,1\right), \\ \sigma_{t+1}^2 &= \omega + \beta \sigma_t^2 + \alpha \mathbf{y}_t^2, \\ \sigma_{t+1}^2 &= \omega + (\alpha + \beta) \sigma_t^2 + \alpha \Big(\mathbf{y}_t^2 - \sigma_t^2\Big). \end{split}$$

Parameter-driven

Stochastic volatility

$$\begin{split} y_t &= \varepsilon_t, \\ \varepsilon_t &= \eta_t \exp\left(\frac{1}{2}\sigma_t\right), \qquad \eta_t \sim \mathsf{N}\left(0,1\right), \\ \sigma_{t+1} &= \omega + \beta\sigma_t + \zeta_t, \qquad \zeta_t \sim \mathsf{N}\left(0,\sigma_\zeta^2\right). \end{split}$$



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Nelson (1992, JE) shows that GARCH(1,1) produces consistent paths, even if the true DGP is the SV.



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1. Use GARCH(1,1) to get $\hat{\sigma}_t^2$ and fitted residuals $\hat{\varepsilon}_t$, get raw residuals: $\hat{\eta}_t = \hat{\varepsilon}_t (\hat{\sigma}_t)^{-1}$.



Hall and Yao (2003); Gonçalves and Kilian (2004); Pascual, Romo, and Ruiz (2006)

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LITE bootstrap

$$\sigma_{t} = \varepsilon_{t} = \eta_{t} \sqrt{\sigma_{t}^{2}}, \quad \eta_{t} \sim N(0, 1), \quad \sigma_{t+1}^{2} = \omega + \beta \sigma_{t}^{2} + \alpha \gamma_{t}^{2}$$

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LITE resampler

$$u_t = \varepsilon_t = \eta_t \sqrt{\sigma_t^2}, \quad \eta_t \sim N(0, 1), \quad \sigma_{t+1}^2 = \omega + \beta \sigma_t^2 + \alpha y_t^2$$

Instead of *i.i.d.*, the LITE resamples residuals in a moving-window fashion. LITE \equiv Local In TimE.



In the neighbourhood of t_1 and t_2 fit of the model is considerably different.



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Minimize average bias of bootstrap paths w.r.t. the GARCH path:

$$\underset{b:\delta(t) \sim \Delta_t^b}{\operatorname{argmin}} \left\{ \frac{1}{n} \sum_t \left[\frac{1}{B} \sum_{i=1}^B \hat{\sigma}_t^{2*} - \hat{\sigma}_t^2 \right]^2 \right\}.$$

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Empirical application

- S&P 500 returns.
- Period: 1980–2015 (9040 daily observations).
- Total return index from Datastream.
- GARCH(1,1) parameters are (with values of the *t*-statistic in parentheses):

$$\begin{split} & \omega = 0.0145(6.5652), \\ & \alpha = 0.0789(13.626), \\ & \beta = 0.910(128.6). \end{split}$$



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Modelling volatility, empirical results

GARCH(1,1)



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Stochastic volatility



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GARCH(1,1) vs. Stochastic volatility



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Realized volatility



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GARCH(1,1) vs. Realized volatility



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True path

A single path of volatility (deterministic or from an SV model) shared across 1,000 Monte Carlo replications. Innovations in the observation equation are drawn as *i.i.d.* N(0,1).

$$\begin{split} y_t &= \varepsilon_t, \\ \varepsilon_t &= \eta_t \sigma_t, \\ \eta_t &\sim \mathsf{N}\left(0,1\right). \end{split}$$

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- True path -- Median GARCH(1,1) = GARCH MC 90% conf. band

Given the 1,000 GARCH paths, I construct a 'GARCH MC' confidence band as a benchmark. This is the best the GARCH filter can be expected to do.

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- LITE bands have unconditional coverage of ca. 77%.
- The benchmark, GARCH MC, is at 84%.
- Coverage is not uniform and depends on the value of volatility itself.



LITE bootstrap + LITE resampler, convergence



True path

Increase number of observations from 6,952 days to 50,000.

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Daily, 6,952 observations



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7x, 50,000 observations





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Daily, 6,952 observations



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7x, 50,000 observations





Daily, 6,952 observations





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Daily, 6,952 observations



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7x, 50,000 observations





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- Risk budgeting
- Ensemble estimators
- VaR, ES
- Trading (based on span or asymmetry)





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- **Risk budgeting** •
- Ensemble estimators .
- VaR, ES
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Filtering With Confidence



Correlation

Lucas, Schwaab, and Zhang (2015 JAE), Oh and Patton (2013)



Systemic risk

Lucas, Schwaab, and Zhang (2015 JAE), Oh and Patton (2013)



Loss-Given-Default Creal, Schwaab, Koopman, and Lucas (2014 REStat)



Term structure of interest rates slope from Diebold, Li, Yue (2008 JE)



Stochastic Volatility with jumps Johannes, Polson, Stroud (2009 RFS)



Business and financial cycles

Galati, Hindrayanto, Koopman, and Vlekke (2015)



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Conclusions

- A novel bootstrap approach combined with a new resampling scheme.
- Produces in-sample confidence bands around time-varying parameters in observation-driven models.
- Accounts for parameter and filtering uncertainty.
- Average coverage converges to the nominal level.
- Easily implementable and a flexible method.
- Can be used as a smoother to mitigate attenuation bias.



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Really easy

```
function sample locally(rng, b)
        out=collect(rng)
        out[b+1:N-b]=sample(-b:b, length(b+1:N-b))+out[b+1:N-b]
        for i in unique([1:b; N-b+1:N])
            if i>=1 && i<=N
                 rng=maximum([1,i-b]):minimum([N,i+b])
                 out[i]=sample(rng,1)[1]
            end
        end
        return out
11 end
13 σ, ε, params=fit_garch(params, y);
14
15 #Normalized residuals
16 normalized_residuals= ε ./ σ;
17 normalized residuals-=mean(normalized residuals):
19 #Running bootstrap
20 paths=zeros(T,B+1); paths[:, end]=g;
21 for i=1:B
       y<sup>B</sup>=normalized residuals[sample locally(1:T, bandwidth)] \star \sigma;
        \sigma^{B}, \epsilon^{B}, params<sup>B</sup>=fit_garch(params, y<sup>B</sup>);
        paths[i,:]=\sigma^{B};
24
25 end
26 get bands(paths)
```

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LITE bootstrap + *I.I.D.* resampler \rightarrow mess



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